

Premisse

three normal coords:

$$R_{ab}{}^c{}_d = 2\Gamma_b{}^c{}_d - 2\Gamma_a{}^c{}_d$$

$$R_{abcd} = \frac{1}{2} \left( g_{cd,ab} + g_{bc,ad} - g_{bd,ac} \right)$$

$$- \frac{1}{2} \left( g_{ab,cd} + g_{ac,bd} - g_{ad,bc} \right)$$

$$\Gamma_b{}^c{}_d = \frac{1}{2} g^{ce} \left( g_{bd,c} - g_{cd,b} \right)$$

$$- g_{bd,e}$$

Ret'n w/ regard to  $\epsilon_{123}$ : in 2d rep

$$g_{...} \in \text{Fix } ((12))$$

Extra ret'n (torsion free)  
 $(1 + ((12) \times ((12)^2))) g_{...} = 0$

From geod eq'n  $\nabla r = g^{rcl} \nabla r$

$$-(12)$$

$$-(34)$$

$$1 \sim \sigma^2$$

$$\begin{matrix} \text{act} \\ \text{but} \end{matrix}$$

$$\begin{matrix} \text{act} \\ \text{act} \end{matrix}$$

Gauss's lemma:  $r \partial_r = \nabla r$   $r dr = \delta_{ij} x^i dx^j$

$$\langle x^i \partial_i, \partial_r \rangle = \langle g^{jk} \delta_{ij} x^i \partial_k, \partial_r \rangle$$

$$x^i g_{ie} = \delta_{ir} x^i$$

$$x^i g_{ie} = x^i \delta_{ir} + \underbrace{x^i \alpha_{rik} x^k}_{=0}$$

$$\Leftrightarrow \sum_{e \in S_3} \alpha_{reie} = 0$$

$$\frac{x^i \partial_i}{r} = \underbrace{g^{ij} \frac{x^i \partial_j}{r}}_{=0}$$

$$x^i = g^{ij} x^j$$

$$= x^i - g_{ik}{}_{lk} x^k x^l x^i$$

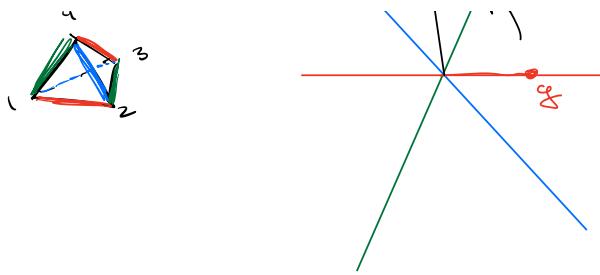
$$\Rightarrow g_{...} \in \text{Fix also}$$

$$\rightsquigarrow (13)(24) \text{ acts trivially}$$

$$\Rightarrow R_{abcd} = g_{ad,cb} - g_{ac,bd}$$

$$R = ((24) - (23)) g$$





Normal coordinate trick: 2nd Bianchi identity

Use normal coords when you run to loop terms!

$$\nabla_a \nabla_b \nabla_c \varphi_d - \nabla_b \nabla_a \nabla_c \varphi_d = R(a, b)(\nabla_c \varphi_d) = 0$$

$$2 \cancel{z} 1 - 1 \cancel{3} 2$$

$$1 \cancel{2} 3 - 2 \cancel{1} 3$$

$$3 \cancel{1} 2 - 3 \cancel{2} 1$$

Recall we determine  $R$

Con  $\mathbb{R}$   $ac = C$  then

$$R(X, Y)Z = C(\langle X, Z \rangle Y - \langle Y, Z \rangle X)$$

↑ check Riccati:

$$\langle W, R(X, Y)Z \rangle$$

$\Leftrightarrow$

$$((\lambda - \sigma^2)(1 - \langle Z, Z \rangle) - (\lambda - \sigma^2)(1 - \langle Z, Z \rangle)) = 0 \quad \downarrow$$

let  $u(t) = \begin{cases} t & C=0 \\ \frac{\lambda - \sigma^2}{2}t & C = \frac{1}{2}\sigma^2 > 0 \\ \frac{\lambda - \sigma^2}{2}t & C = -\frac{1}{2}\sigma^2 < 0 \end{cases}$

Then if  $(M, g)$  has const. sec. curvature  $C$  then it is locally isometric to  $(\mathbb{S}^2 \times U_c(r)^2 g_{\text{can}})$

↑

conquer from 2

$$B = \frac{1}{2}g^{-1}dg$$

$$\int_B B + B^2 = -R_{2r} = R(2r, X)2r = -C I \quad \text{on } \mathbb{R}^2$$

$$\boxed{R_{2r} = -R(2r, X)2r = R(X, 2r)2r}$$

Hypothetical plane models

## Waves outside

Date geodesics are easier to find than distance functions.  
so choosing things in terms of Sasaki  
Fields is a little more general.

in general, Riemann  
of geodesics  
just relate!

Prop  $\mathcal{J}$  is tangent to a variation thru geodesics iff

$$\nabla_{\partial_t} \mathcal{J} = -R_g(\mathcal{J})$$

Def'n to the Riccati eqn

↑ picks out a Lagrangian subspace of the 2n-dim'l  
space of Sasaki Fields, namely  $\{\mathcal{J} \text{ s.t. } \mathcal{L}_{\mathcal{X}} \mathcal{J} = 0\}$

Link  $\mathcal{L}_{\mathcal{X}} \mathcal{J} = 0$  makes sense

$$(\mathcal{L}_{\mathcal{X}}^g TM) = \text{Der}(C^\infty(M), \mathcal{O}(TM)_e)$$

$\mathcal{L}_{\mathcal{X}} \mathcal{J} = -\mathcal{D}_{\mathcal{X}} \mathcal{J}$  makes sense b/c  $\mathcal{D}_{\mathcal{X}} \in \text{Der}(\mathcal{O}(TM))$  also

$$\mathcal{L}_{\mathcal{X}} \mathcal{J} = \nabla_{\mathcal{X}} \mathcal{J} - \nabla_{\mathcal{J}} \mathcal{X} = \nabla_{\mathcal{X}} \mathcal{J} - B(\mathcal{J})$$

If  $\nabla_{\mathcal{X}} \mathcal{J} = B(\mathcal{J})$  i.e.  $\mathcal{L}_{\mathcal{X}} \mathcal{J} = 0$ , then

$$(\mathcal{L}_{\mathcal{X}} B)(\mathcal{J}) + B^2 \mathcal{J} = \nabla_{\mathcal{X}} \nabla_{\mathcal{X}} \mathcal{J}$$

2nd von Riemann - type form. (7.)

Sol'n w/  $\mathcal{J}(o) = 0$  determined by  $D_{\mathcal{X}} \mathcal{J}(o) \in T_o$

→ Metric on  $S^{n-1}$